

Code of the multidimensional fractional quasi-Newton method using recursive programming

A. Torres-Hernandez ^{*,a}

^aDepartment of Physics, Faculty of Science - UNAM, Mexico

Abstract

The following paper presents one way to define and classify the fractional quasi-Newton method through a group of fractional matrix operators, as well as a code written in recursive programming to implement this method, which through minor modifications, can be implemented in any fractional fixed-point method that allows solving nonlinear algebraic equation systems.

Keywords: Fractional Operators; Group Theory; Fractional Iterative Methods; Recursive Programming.

1. FRACTIONAL QUASI-NEWTON METHOD

To begin this section, it is necessary to mention that due to the large number of fractional operators that may exist [1–6], some sets must be defined to fully characterize the **fractional quasi-Newton method**¹ [7, 8]. It is worth mentioning that characterizing elements of fractional calculus through sets is the main idea behind of the methodology known as **fractional calculus of sets** [9]. So, considering a scalar function $h : \mathbb{R}^m \rightarrow \mathbb{R}$ and the canonical basis of \mathbb{R}^m denoted by $\{\hat{e}_k\}_{k \geq 1}$, it is possible to define the following fractional operator of order α using Einstein notation

$$o_x^\alpha h(x) := \hat{e}_k o_k^\alpha h(x). \quad (1)$$

Therefore, denoting by ∂_k^n the partial derivative of order n applied with respect to the k -th component of the vector x , using the previous operator it is possible to define the following set of fractional operators

$$O_{x,\alpha}^n(h) := \left\{ o_x^\alpha : \exists o_k^\alpha h(x) \text{ and } \lim_{\alpha \rightarrow n} o_k^\alpha h(x) = \partial_k^n h(x) \forall k \geq 1 \right\}, \quad (2)$$

whose complement may be defined as follows

$$O_{x,\alpha}^{n,c}(h) := \left\{ o_x^\alpha : \exists o_k^\alpha h(x) \forall k \geq 1 \text{ and } \lim_{\alpha \rightarrow n} o_k^\alpha h(x) \neq \partial_k^n h(x) \text{ in at least one value } k \geq 1 \right\}, \quad (3)$$

as a consequence, it is possible to define the following set

$$O_{c,x,\alpha}^{n,u}(h) := \left(O_{x,\alpha}^n(h) \cup O_{x,\alpha}^{n,c}(h) \right) \cap \left\{ o_x^\alpha : o_c^\alpha \neq 0 \forall c \in \mathbb{R} \setminus \{0\} \text{ and } \forall k \geq 1 \right\}. \quad (4)$$

On the other hand, considering a linear function $h : \Omega \subset \mathbb{R}^m \rightarrow \mathbb{R}^m$, it is possible to define the following set

$${}_m O_{c,x,\alpha}^{n,u}(h) := \left\{ o_x^\alpha : o_c^\alpha \in O_{c,x,\alpha}^{n,u}([h]_k) \forall k \leq m \right\}, \quad (5)$$

*E-mail: anthony.torres@ciencias.unam.mx; ORCID: 0000-0001-6496-9505

¹Método quasi-Newton fraccional.

where $[h]_k : \Omega \subset \mathbb{R}^m \rightarrow \mathbb{R}$ denotes the k -th component of the function h . So, it is possible to define the following set of fractional operators

$${}_m \text{MO}_{c,x,\alpha}^{\infty,u}(h) := \bigcap_{k \in \mathbb{Z}} {}_m \text{O}_{c,x,\alpha}^{k,u}(h), \tag{6}$$

which under the classical Hadamard product it is fulfilled that

$$o_x^0 \circ h(x) := h(x) \quad \forall o_x^\alpha \in {}_m \text{MO}_{c,x,\alpha}^{\infty,u}(h). \tag{7}$$

Then, considering that for each operator o_x^α it is possible to define the following **fractional matrix operator**

$$A_\alpha(o_x^\alpha) = ([A_\alpha(o_x^\alpha)]_{jk}) = (o_k^\alpha), \tag{8}$$

it is possible to define the following set of fractional operators

$${}_m \text{IMO}_{c,x,\alpha}^{\infty,u}(h) := {}_m \text{MO}_{c,x,\alpha}^{\infty,u}(h) \cap \left\{ o_x^\alpha : \exists (A_\alpha(o_x^\alpha) \circ A_\alpha^T(h))^{-1} \right\}, \tag{9}$$

where $A_\alpha(h) = ([A_\alpha(h)]_{jk}) = ([h]_k)$. On the other hand, considering that when using the classical Hadamard product in general $o_x^{p\alpha} \circ o_x^{q\alpha} \neq o_x^{(p+q)\alpha}$. It is possible to define the following modified Hadamard product [9]:

$$o_{i,x}^{p\alpha} \circ o_{j,x}^{q\alpha} := \begin{cases} o_{i,x}^{p\alpha} \circ o_{j,x}^{q\alpha}, & \text{if } i \neq j \text{ (Hadamard product of type horizontal)} \\ o_{i,x}^{(p+q)\alpha}, & \text{if } i = j \text{ (Hadamard product of type vertical)} \end{cases}, \tag{10}$$

with which it is possible to obtain the following theorem:

Theorem 1. Let o_x^α be a fractional operator such that $o_x^\alpha \in {}_m \text{MO}_{c,x,\alpha}^{\infty,u}(h)$. So, considering the modified Hadamard product given by (10), it is possible to define the following set of fractional matrix operator

$${}_m \text{G}(A_\alpha(o_x^\alpha)) := \left\{ A_\alpha^{or} = A_\alpha(o_x^{r\alpha}) : r \in \mathbb{Z} \text{ and } A_\alpha^{or} = ([A_\alpha^{or}]_{jk}) := (o_k^{r\alpha}) \right\}, \tag{11}$$

which corresponds to the Abelian group generated by the operator $A_\alpha(o_x^\alpha)$.

Proof. It should be noted that due to the way the set (11) is defined, just the Hadamard product of type vertical is applied among its elements. So, $\forall A_\alpha^{op}, A_\alpha^{oq} \in {}_m \text{G}(A_\alpha(o_x^\alpha))$ it is fulfilled that

$$A_\alpha^{op} \circ A_\alpha^{oq} = ([A_\alpha^{op}]_{jk}) \circ ([A_\alpha^{oq}]_{jk}) = (o_k^{(p+q)\alpha}) = ([A_\alpha^{o(p+q)}]_{jk}) = A_\alpha^{o(p+q)}, \tag{12}$$

with which it is possible to prove that the set (11) fulfills the following properties, which correspond to the properties of an Abelian group:

$$\left\{ \begin{array}{l} \forall A_\alpha^{op}, A_\alpha^{oq}, A_\alpha^{or} \in {}_m \text{G}(A_\alpha(o_x^\alpha)) \text{ it is fulfilled that } (A_\alpha^{op} \circ A_\alpha^{oq}) \circ A_\alpha^{or} = A_\alpha^{op} \circ (A_\alpha^{oq} \circ A_\alpha^{or}) \\ \exists A_\alpha^{o0} \in {}_m \text{G}(A_\alpha(o_x^\alpha)) \text{ such that } \forall A_\alpha^{op} \in {}_m \text{G}(A_\alpha(o_x^\alpha)) \text{ it is fulfilled that } A_\alpha^{o0} \circ A_\alpha^{op} = A_\alpha^{op} \\ \forall A_\alpha^{op} \in {}_m \text{G}(A_\alpha(o_x^\alpha)) \exists A_\alpha^{o-p} \in {}_m \text{G}(A_\alpha(o_x^\alpha)) \text{ such that } A_\alpha^{op} \circ A_\alpha^{o-p} = A_\alpha^{o0} \\ \forall A_\alpha^{op}, A_\alpha^{oq} \in {}_m \text{G}(A_\alpha(o_x^\alpha)) \text{ it is fulfilled that } A_\alpha^{op} \circ A_\alpha^{oq} = A_\alpha^{oq} \circ A_\alpha^{op} \end{array} \right. \tag{13}$$

□

From the previous theorem, it is possible to define the following group of fractional matrix operators [9]:

$${}_m G_{FQN}(\alpha) := \bigcup_{o_x^\alpha \in {}_m \text{IMO}_{c,x,\alpha}^{\infty,u}(h)} {}_m G(A_\alpha(o_x^\alpha)), \quad (14)$$

where $\forall A_{i,\alpha}^{\circ p}, A_{j,\alpha}^{\circ q} \in {}_m G_{FQN}(\alpha)$, with $i \neq j$, the following property is defined

$$A_{i,\alpha}^{\circ p} \circ A_{j,\alpha}^{\circ q} = A_{k,\alpha}^{\circ 1} := A_{k,\alpha}(o_{i,x}^{p\alpha} \circ o_{j,x}^{q\alpha}), \quad p, q \in \mathbb{Z} \setminus \{0\}, \quad (15)$$

as a consequence, it is fulfilled that

$$\forall A_{k,\alpha}^{\circ 1} \in {}_m G_{FQN}(\alpha) \text{ such that } A_{k,\alpha}(o_{k,x}^\alpha) = A_{k,\alpha}(o_{i,x}^{p\alpha} \circ o_{j,x}^{q\alpha}) \exists A_{k,\alpha}^{\circ r} = A_{k,\alpha}^{\circ(r-1)} \circ A_{k,\alpha}^{\circ 1} = A_{k,\alpha}(o_{i,x}^{rp\alpha} \circ o_{j,x}^{rq\alpha}). \quad (16)$$

Then, it is possible to obtain the following result:

$$\forall A_\alpha^{\circ 1} \in {}_m G_{FQN}(\alpha) \exists A_{h,\alpha}^{-1} := A_\alpha(o_x^\alpha) \circ A_\alpha^T(h), \quad (17)$$

and defining the following function

$$\beta(\alpha, [x]_k) := \begin{cases} \alpha, & \text{if } |[x]_k| \neq 0 \\ 1, & \text{if } |[x]_k| = 0 \end{cases}, \quad (18)$$

the fractional quasi-Newton method may be defined and classified through the following set of matrices:

$$\{A_{h,\beta} = A_{h,\beta}(A_\alpha^{\circ 1}) : A_\alpha^{\circ 1} \in {}_m G_{FQN}(\alpha) \text{ and } A_{h,\beta}(x) = ([A_{h,\beta}]_{jk}(x))\}. \quad (19)$$

Therefore, if Φ_{FQN} denotes the iteration function of the fractional quasi-Newton method, it is possible to obtain the following result:

$$\text{Let } \alpha_0 \in \mathbb{R} \setminus \mathbb{Z} \Rightarrow \forall A_{\alpha_0}^{\circ 1} \in {}_m G_{FQN}(\alpha) \exists \Phi_{FQN} = \Phi_{FQN}(A_{\alpha_0}) \therefore \forall A_{\alpha_0} \exists \{\Phi_{FQN}(A_\alpha) : \alpha \in \mathbb{R} \setminus \mathbb{Z}\}. \quad (20)$$

To end this section, it is worth mentioning that the fractional quasi-Newton method has been used in the study for the construction of hybrid solar receivers [8], and that in recent years there has been a growing interest in fractional operators and their properties for solving nonlinear algebraic equation systems [7, 10–18].

2. PROGRAMMING CODE OF FRACTIONAL QUASI-NEWTON METHOD

The following code was implemented in Python 3 and requires the following packages:

```
1 import math as mt
2 import numpy as np
3 from numpy import linalg as la
```

For simplicity, a two-dimensional vector function is used to implement the code, that is, $f : \Omega \subset \mathbb{R}^2 \rightarrow \mathbb{R}^2$, which may be denoted as follows:

$$f(x) = \begin{pmatrix} [f]_1(x) \\ [f]_2(x) \end{pmatrix}, \quad (21)$$

where $[f]_i : \Omega \subset \mathbb{R}^2 \rightarrow \mathbb{R} \forall i \in \{1, 2\}$. Then considering a function $\Phi : (\mathbb{R} \setminus \mathbb{Z}) \times \mathbb{C}^n \rightarrow \mathbb{C}^n$, the fractional quasi-Newton method may be denoted as follows [8, 9]:

$$x_{i+1} := \Phi(\alpha, x_i) = x_i - A_{g,f,\beta}(x_i)f(x_i), \quad i = 0, 1, 2, \dots, \quad (22)$$

where $A_{g_f, \beta}(x_i)$ is a matrix evaluated in the value x_i , which is given by the following expression

$$A_{g_f, \beta}(x_i) = ([A_{g_f, \beta}]_{jk}(x_i)) := \left(o_k^{\beta(\alpha, [x_i]_k)} [g_f]_j(x) \right)_{x_i}^{-1}, \tag{23}$$

with $g_f(x) := f(x_i) + f^{(1)}(x_i)x$. It is worth mentioning that one of the main advantages of fractional iterative methods is that the initial condition x_0 can remain fixed, with which it is enough to vary the order α of the fractional operators involved until generating a sequence convergent $\{x_i\}_{i \geq 1}$ to the value $\xi \in \Omega$. Since the order α of the fractional operators is varied, different values of α can generate different convergent sequences to the same value ξ but with a different number of iterations. So, it is possible to define the following set

$$\text{Conv}_\delta(\xi) := \left\{ \Phi : \lim_{x \rightarrow \xi} \Phi(\alpha, x) = \xi_\alpha \in B(\xi; \delta) \right\}, \tag{24}$$

which may be interpreted as the set of fractional fixed-point methods that define a convergent sequence $\{x_i\}_{i \geq 1}$ to some value $\xi_\alpha \in B(\xi; \delta)$. So, denoting by $\text{card}(\cdot)$ the cardinality of a set, under certain conditions it is possible to prove the following result (see reference [9], proof of **Theorem 2**):

$$\text{card}(\text{Conv}_\delta(\xi)) = \text{card}(\mathbb{R}), \tag{25}$$

from which it follows that the set (24) is generated by an uncountable family of fractional fixed-point methods. Before continuing, it is necessary to define the following corollary [9]:

Corollary 1. *Let $\Phi : (\mathbb{R} \setminus \mathbb{Z}) \times \mathbb{C}^n \rightarrow \mathbb{C}^n$ be an iteration function such that $\Phi \in \text{Conv}_\delta(\xi)$. So, if Φ has an order of convergence of order (at least) p in $B(\xi; 1/2)$, for some $m \in \mathbb{N}$, there exists a sequence $\{P_i\}_{i \geq m} \in B(p; \delta_K)$ given by the following values*

$$P_i = \frac{\log(\|x_i - x_{i-1}\|)}{\log(\|x_{i-1} - x_{i-2}\|)}, \tag{26}$$

such that it fulfills the following condition:

$$\lim_{i \rightarrow \infty} P_i \rightarrow p,$$

and therefore, there exists at least one value $k \geq m$ such that

$$P_k \in B(p; \epsilon). \tag{27}$$

The previous corollary allows estimating numerically the order of convergence of an iteration function Φ that generates at least one convergent sequence $\{x_i\}_{i \geq 1}$. On the other hand, the following corollary allows characterizing the order of convergence of an iteration function Φ through its **Jacobian matrix** $\Phi^{(1)}$ [9, 18]:

Corollary 2. *Let $\Phi : (\mathbb{R} \setminus \mathbb{Z}) \times \mathbb{C}^n \rightarrow \mathbb{C}^n$ be an iteration such that $\Phi \in \text{Conv}_\delta(\xi)$. So, if Φ has an order of convergence of order (at least) p in $B(\xi; \delta)$, it is fulfilled that:*

$$p := \begin{cases} 1, & \text{if } \lim_{x \rightarrow \xi} \|\Phi^{(1)}(\alpha, x)\| \neq 0 \\ 2, & \text{if } \lim_{x \rightarrow \xi} \|\Phi^{(1)}(\alpha, x)\| = 0 \end{cases}. \tag{28}$$

Before continuing it is necessary to mention that what is shown below is an extremely simplified way of how a fractional iterative method should be implemented, a more detailed description, as well as some applications, may be found in the references [7–9, 17–19]. Considering the following notation:

$$\text{ErrDom} := \{\|x_i - x_{i-1}\|_2\}_{i \geq 1}, \quad \text{ErrIm} := \{\|f(x_i)\|_2\}_{i \geq 1}, \quad X := \{x_i\}_{i \geq 1}, \tag{29}$$

it is possible to implement a particular case of the multidimensional fractional quasi-Newton method through recursive programming using the following functions:

```

1 def Dfrac( $\alpha, \mu, x$ ):
2     s= $\mu-\alpha$ 
3     if  $\mu>-1$ :
4         return (mt.gamma( $\mu+1$ )/mt.gamma(s+1))*pow(complex(x),s) if mt.ceil(s)-s>0 or s>-1 else 0
5
6 def  $\beta(\alpha, x)$ :
7     return  $\alpha$  if abs(x)>0 else 1
8
9 def FractionalQuasiNewton(ErrDom,ErrIm,X, $\alpha, x_0$ ):
10    Tol=pow(10,-5)
11    Lim=pow(10,2)
12    InvA=InvAgf $\beta(\alpha, x_0)$ 
13
14    if abs(la.det(InvA))>0:
15        x1=x0-np.matmul(la.inv(InvA),f(x0))
16        ED=la.norm(x1-x0)
17
18        if ED>0:
19            EI=la.norm(f(x1))
20
21            ErrDom.append(ED)
22            ErrIm.append(EI)
23            X.append(x1)
24            N=len(X)
25
26            if max(ED,EI)>Tol and N<Lim:
27                ErrDom,ErrIm,X=FractionalQuasiNewton(ErrDom,ErrIm,X, $\alpha, x_1$ )
28
29    return ErrDom,ErrIm,X

```

To implement the above functions, it is necessary to follow the steps shown below:

i) A function must be programmed together with its Jacobian matrix.

```

1 def f(x):
2     y=np.zeros((2,1)).astype(complex)
3     y[0]=np.sin(x[0])*pow(x[0],2)+ np.cos(x[1])*pow(x[1],3)-5
4     y[1]=np.cos(x[0])*pow(x[0],3)-np.sin(x[1])*pow(x[1],2)-7
5     return y
6
7 def Df(x):
8     y=np.zeros((2,2)).astype(complex)
9     y[0][0]=2*np.sin(x[0])*x[0]+np.cos(x[0])*pow(x[0],2)
10    y[0][1]=3*np.cos(x[1])*pow(x[1],2)-np.sin(x[1])*pow(x[1],3)
11    y[1][0]=3*np.cos(x[0])*pow(x[0],2)-np.sin(x[0])*pow(x[0],3)
12    y[1][1]=-2*np.sin(x[1])*x[1]-np.cos(x[1])*pow(x[1],2)
13    return y

```

ii) The matrix $A_{gf,\beta}^{-1}$ must be programmed.

```

1 def InvAgf $\beta(\alpha, x)$ :
2     f0=f(x)
3     Df0=Df(x)
4
5     g11=f0[0]
6     g1x=Df0[0][0]
7     g1y=Df0[0][1]
8
9     g21=f0[1]
10    g2x=Df0[1,0]
11    g2y=Df0[1,1]
12
13     $\beta_1=\beta(\alpha, x[0])$ 
14     $\beta_2=\beta(\alpha, x[1])$ 
15
16    y=np.zeros((2,2)).astype(complex)
17    y[0][0]=(g11+g1y*x[1])*Dfrac( $\beta_1, 0, x[0]$ )+ g1x*Dfrac( $\beta_1, 1, x[0]$ )
18    y[0][1]=(g11+g1x*x[0])*Dfrac( $\beta_2, 0, x[1]$ )+ g1y*Dfrac( $\beta_2, 1, x[1]$ )
19    y[1][0]=(g21+g2y*x[1])*Dfrac( $\beta_1, 0, x[0]$ )+ g2x*Dfrac( $\beta_1, 1, x[0]$ )
20    y[1][1]=(g21+g2x*x[0])*Dfrac( $\beta_2, 0, x[1]$ )+ g2y*Dfrac( $\beta_2, 1, x[1]$ )
21    return y

```

iii) Three empty vectors, a fractional order α , and an initial condition x_0 must be defined before implementing the function FractionalQuasiNewton.

```

1 ErrDom=[]
2 ErrIm=[]
3 X=[]
4
5  $\alpha = -0.14154$ 
6
7  $x_0 = 1.87 * \text{np.ones}((2, 1))$ 
8
9 ErrDom, ErrIm, X = FractionalQuasiNewton(ErrDom, ErrIm, X,  $\alpha$ ,  $x_0$ )
    
```

When implementing the previous steps, if the fractional order α and initial condition x_0 are adequate to approach a zero of the function f , results analogous to the following are obtained:

i	$[x_i]_1$	$[x_i]_2$	$\ x_i - x_{i-1}\ _2$	$\ f(x_i)\ _2$
1	2.253615105769526	1.1942449832449582	0.7770491567746352	15.554324370388906
2	-3.9004625603638927	7.157573208896508	8.569361437566664	240.708834467148
3	$-1.5541583533037069 - 1.1179838230007044i$	$4.4928672793164015 - 2.962300422113517e - 15i$	3.722323058480951	27.692687964920736
4	$-1.944385547081847 - 1.0897773339058576i$	$4.940730623672673 - 0.13817042653542763i$	0.6105288779230554	29.219708233069287
5	$-1.8475774337627011 - 1.1801485625387642i$	$4.855392369520536 + 0.009503969164296189i$	0.21593775616146188	8.81592186304761
6	$-1.7960511251389712 - 1.250743007942112i$	$4.8220026103345015 + 0.10421795336899867i$	0.13313208112481426	5.23303705045184
⋮	⋮	⋮	⋮	⋮
41	$-1.76751483239573 - 1.2381890934335078i$	$4.798857098280522 + 0.06489785685468008i$	$9.746530597591146e - 07$	$7.151481519961957e - 05$
42	$-1.7675150566379345 - 1.2381893834982014i$	$4.798857321824474 + 0.06489811797226702i$	$5.025697814069152e - 07$	$8.392901211001586e - 05$
43	$-1.7675149484191435 - 1.2381895859611525i$	$4.798857156145471 + 0.06489836899944432i$	$3.783737954105193e - 07$	$6.69477928230414e - 05$
44	$-1.7675147384551197 - 1.2381895971905954i$	$4.798856853548587 + 0.06489842891980367i$	$3.7331798114472574e - 07$	$3.9363864098046455e - 05$
45	$-1.7675145927812685 - 1.2381894810754603i$	$4.798856620324174 + 0.0648983327382783i$	$3.1360501942818643e - 07$	$1.4419381217770664e - 05$
46	$-1.767514555643636 - 1.2381893489293105i$	$4.798856526732281 + 0.06489819878007232i$	$2.1341521058220815e - 07$	$4.62494486008204e - 06$

Table 1: Results obtained using the fractional quasi-Newton method [8].

Therefore, from the Corollary 1, the following result is obtained:

$$P_{46} = \frac{\log(\|x_{46} - x_{45}\|)}{\log(\|x_{45} - x_{44}\|)} \approx 1.0257 \in B(p; \delta_K),$$

which is consistent with the Corollary 2, since if $\Phi_{FQN} \in \text{Conv}_\delta(\xi)$, in general Φ_{FQN} fulfills the following condition (see reference [18], proof of Proposition 1):

$$\lim_{x \rightarrow \xi} \left\| \Phi_{FQN}^{(1)}(\alpha, x) \right\| \neq 0, \tag{30}$$

from which it is concluded that the fractional quasi-Newton method has an order of convergence (at least) linear in $B(\xi; \delta)$.

REFERENCES

- [1] José A Tenreiro Machado et al. A review of definitions for fractional derivatives and integral. *Mathematical Problems in Engineering*, pages 1–6, 2014.
- [2] G Sales Teodoro, JA Tenreiro Machado, and E Capelas De Oliveira. A review of definitions of fractional derivatives and other operators. *Journal of Computational Physics*, 388:195–208, 2019.
- [3] Mehmet Yavuz and Necati Özdemir. Comparing the new fractional derivative operators involving exponential and mittag-leffler kernel. *Discrete & Continuous Dynamical Systems-S*, 13(3):995, 2020.
- [4] M Abu-Shady and Mohammed KA Kaabar. A generalized definition of the fractional derivative with applications. *Mathematical Problems in Engineering*, 2021.
- [5] Khaled M Saad. New fractional derivative with non-singular kernel for deriving legendre spectral collocation method. *Alexandria Engineering Journal*, 59(4):1909–1917, 2020.

- [6] Jian-Gen Liu, Xiao-Jun Yang, Yi-Ying Feng, and Ping Cui. New fractional derivative with sigmoid function as the kernel and its models. *Chinese Journal of Physics*, 68:533–541, 2020.
- [7] A. Torres-Hernandez, F. Brambila-Paz, and E. De-la-Vega. Fractional newton-raphson method and some variants for the solution of nonlinear systems. *Applied Mathematics and Sciences: An International Journal (MathSJ)*, 7:13–27, 2020. DOI: 10.5121/mathsj.2020.7102.
- [8] A. Torres-Hernandez, F. Brambila-Paz, and R. Montufar-Chaveznavia. Acceleration of the order of convergence of a family of fractional fixed point methods and its implementation in the solution of a nonlinear algebraic system related to hybrid solar receivers. 2021. arXiv preprint arXiv:2109.03152.
- [9] A. Torres-Hernandez and F. Brambila-Paz. Sets of fractional operators and numerical estimation of the order of convergence of a family of fractional fixed-point methods. *Fractal and Fractional*, 5(4):240, 2021. DOI: 10.3390/fractalfract5040240.
- [10] R Erfanifar, K Sayevand, and H Esmaeili. On modified two-step iterative method in the fractional sense: some applications in real world phenomena. *International Journal of Computer Mathematics*, 97(10):2109–2141, 2020.
- [11] Alicia Cordero, Ivan Girona, and Juan R Torregrosa. A variant of chebyshev’s method with 3α th-order of convergence by using fractional derivatives. *Symmetry*, 11(8):1017, 2019.
- [12] Krzysztof Gdawiec, Wiesław Kotarski, and Agnieszka Lisowska. Newton’s method with fractional derivatives and various iteration processes via visual analysis. *Numerical Algorithms*, 86(3):953–1010, 2021.
- [13] Krzysztof Gdawiec, Wiesław Kotarski, and Agnieszka Lisowska. Visual analysis of the newton’s method with fractional order derivatives. *Symmetry*, 11(9):1143, 2019.
- [14] Ali Akgül, Alicia Cordero, and Juan R Torregrosa. A fractional newton method with 2α th-order of convergence and its stability. *Applied Mathematics Letters*, 98:344–351, 2019.
- [15] Giro Candelario, Alicia Cordero, and Juan R Torregrosa. Multipoint fractional iterative methods with $(2\alpha + 1)$ th-order of convergence for solving nonlinear problems. *Mathematics*, 8(3):452, 2020.
- [16] Giro Candelario, Alicia Cordero, Juan R Torregrosa, and María P Vassileva. An optimal and low computational cost fractional newton-type method for solving nonlinear equations. *Applied Mathematics Letters*, 124:107650, 2022.
- [17] A. Torres-Hernandez and F. Brambila-Paz. Fractional newton-raphson method. *Applied Mathematics and Sciences: An International Journal (MathSJ)*, 8:1–13, 2021. DOI: 10.5121/mathsj.2021.8101.
- [18] A. Torres-Hernandez, F. Brambila-Paz, U. Iturrarán-Viveros, and R. Caballero-Cruz. Fractional newton-raphson method accelerated with aitken’s method. *Axioms*, 10(2):1–25, 2021. DOI: 10.3390/axioms10020047.
- [19] A. Torres-Hernandez, F. Brambila-Paz, P. M. Rodrigo, and E. De-la-Vega. Fractional pseudo-newton method and its use in the solution of a nonlinear system that allows the construction of a hybrid solar receiver. *Applied Mathematics and Sciences: An International Journal (MathSJ)*, 7:1–12, 2020. DOI: 10.5121/mathsj.2020.7201.